Stochastic Particle Algorithms From DSMC to CUBA

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Outline

- Why use stochastic particle methods?
- Direct simulation Monte Carlo (DSMC)
- Selected DSMC applications
- Particle/continuum hybrids
- Dense gases and liquids (CBA & CUBA)
- Future directions

Continuum vs. Particle

When is the continuum description of a gas not accurate?

Knudsen number $\equiv \frac{\text{Mean free path}}{\text{Characteristic length}} = \frac{\lambda}{L}$



High Kn scenarios

- Aerospace flows
- Micromechanical devices
- Fluctuations (e.g., light scattering)
- Shock waves and interfaces

Direct Simulation Monte Carlo

DSMC is a particle-based algorithm for simulating a dilute gas. Particle collisions are evaluated as a stochastic process.

History

- DSMC developed by G.A. Bird (late 60's)
- Popular in aerospace engineering (70's)
- Variants & improvements (early 80's)
- Applications in physics & chemistry (late 80's)
- Used for microscopic flows (early 90's)
- Extended to dense gases & liquids (mid 90's)

DSMC Algorithm

- Initialize system with particles
- Loop over desired number of time steps
 - Create particles at open boundaries
 - Move all the particles
 - Process particle/boundary interactions
 - Select and execute random collisions



DSMC Collisions

- Sort particles into spatial collision cells
- Loop over collision cells
 - Compute collision frequency in a cell
 - Select random collision partners within cell
 - Process each collision



Collisions (cont.)

Probability that a pair collides only depends on their relative velocity.

Post-collision velocities (6 variables) given by:

- Conservation of momentum (3 constraints)
- Conservation of energy (1 constraints)
- Random collision solid angle (2 choices)



Application: Microchannel Flows





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Application: Fluctuations





Continuum/DSMC Hybrids

Problem:

DSMC is computationally expensive

Solution:

Only use DSMC where it is needed

Similar to the idea of mesh refinement

Ordinary Mesh Refinement

Solve equations of the form $\partial_t A = -\nabla \cdot F(A)$ using an explicit PDE solver (e.g., Godunov).

Coarse/Fine Grid Coupling

- Advance coarse grid
- Fill fine/coarse boundary data
 - Advance fine grid
 - Record fluxes at coarse/fine interface
 - Repeat fine grid calculation
- "Reflux" boundary coarse cells
- Backfill overlying coarse cells

Mesh Refinement Illustration

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Mesh and Algorithm Refinement

Coarse/DSMC Coupling

- Advance coarse grid
- Fill DSMC boundary data
 - Create particles in buffer cells
 - Move all particles
 - Record particles crossing interface
 - Discard particles left in buffer region
 - Collide particles within DSMC region
 - Repeat DSMC calculation
- "Reflux" boundary coarse cells
- Backfill overlying coarse cells

MAR Illustration

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Rayleigh Problem



Rayleigh Problem (cont.)



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Flow past a Cylinder





Particles near Cylinder

Sample of particles (1 in 75)



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Particles near Cylinder (cont.)

Particles that struck cylinder (1 in 75)



Dense Gas Variants

DSMC collisions are statistically equivalent to "point" collisions because particle positions are irrelevant in a collision

Problem: DSMC gives ideal gas EOS

Solution:

Modify collisions to give non-zero virial

Consistent Boltzmann Algorithm

Hard sphere displacement



Displacement is parallel to line connecting centers at impact, as determined from pre- and post-collision velocities.

CBA gives exact hard sphere equation of state

CBA Results



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Consistent Universal Boltzmann Algorithm

Magnitude of the displacement varies with density and temperature, according to the desired equation of state.



Van der Waals CUBA



Future Directions

- MAR hybrids using MD, LG or LB
- Particle hybrids (e.g., MD & CBA)
- Statistical mechanics of CUBA models
- Applications (e.g., micromachines)

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Mesh & Algorithm Refinement

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